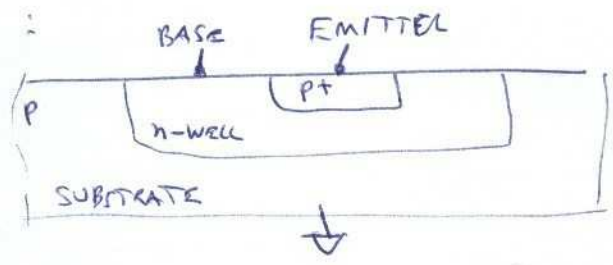


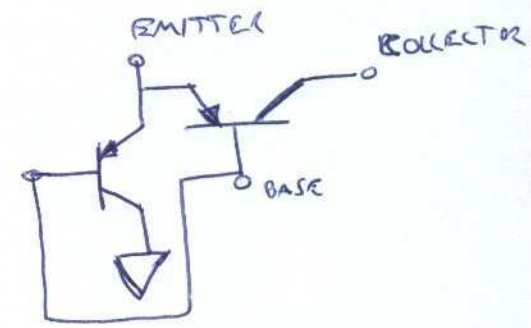
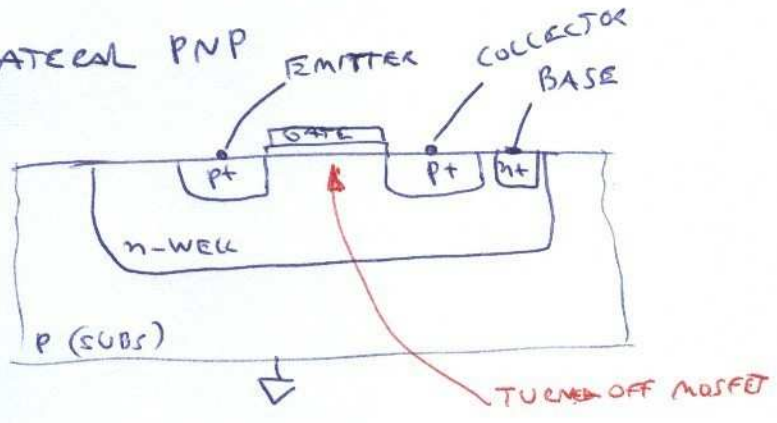
# BIPOLAR TRANSISTORS

- LOWER  $\frac{1}{f}$  NOISE THAN MOSFETS
- BETTER MATCHING
- BAND GAP REFERENCES

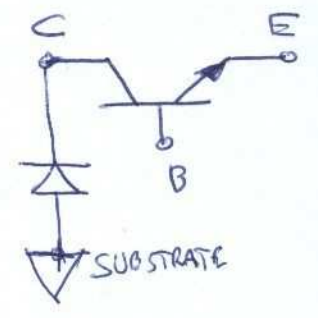
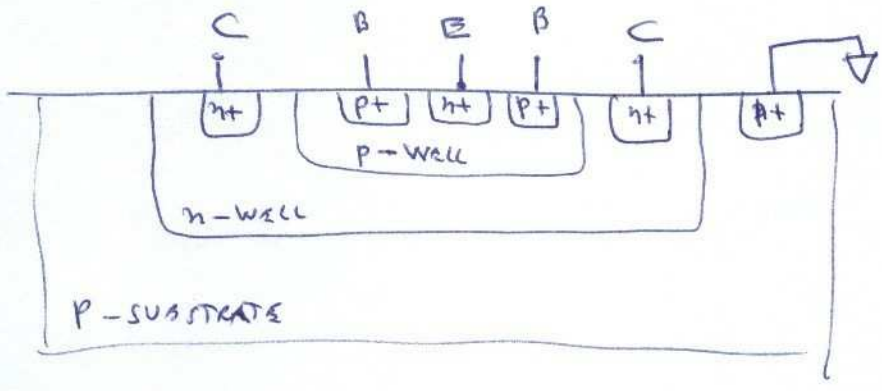
## • VERTICAL PNP :



## • LATERAL PNP



## • VERTICAL NPN IN TRIPLE-WELL CMOS :

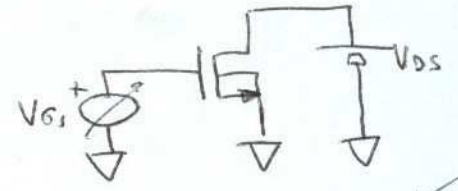
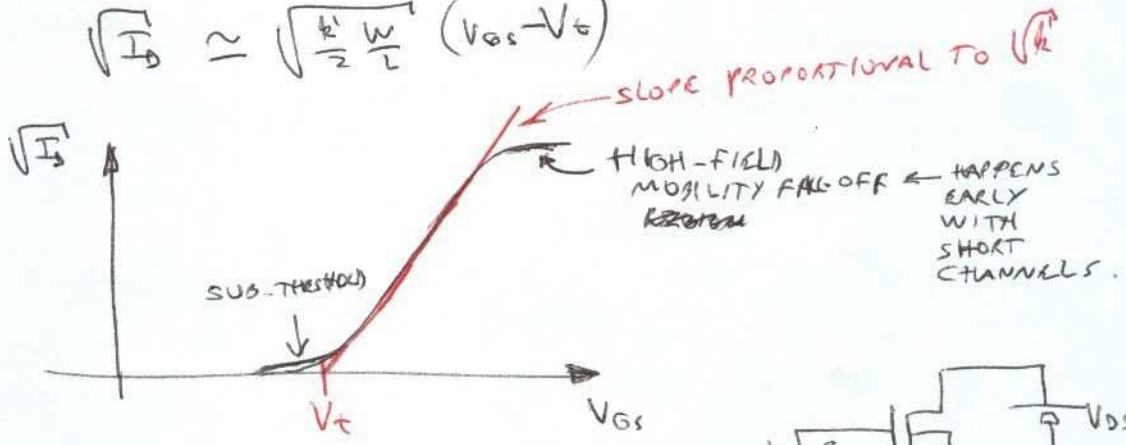


# METHODS TO DETERMINE DESIGN PARAMETERS OF CMOS T. (7)

DETERMINATION OF  $k'$ ,  $V_t$

$$I_D \approx \frac{k'}{2} \frac{W}{L} (V_{GS} - V_t)^2$$

$$\sqrt{I_D} \approx \sqrt{\frac{k'}{2} \frac{W}{L}} (V_{GS} - V_t)$$



3.3V NMOS:

$L = 1 \mu\text{m}$   
 $W = 1.5 \mu\text{m}$   
 $V_{DS} = 1\text{V}$   
 $L_d = 20\text{nm}$

~~$k' = 554.6 \mu\text{A/V}^2$~~   $k' = 137 \mu\text{A/V}^2$   $SLOPE = \frac{4.3 \times 10^{-3}}{4.5 \times 10^{-2}} = 10.3 \times 10^{-3}$

$L_{eff} = 0.96 \mu\text{m}$

$L_d = 20\text{nm}$

$g_{ds} = 181.4 \mu\text{A/V} \Rightarrow \lambda = 0.0075 \text{V}^{-1}$   
 $\frac{dI_D}{dV_{GS}} = L_{eff} \lambda = 0.072 \mu\text{A/V}^2$   
 $\frac{dI_D}{dV_{DS}} = 0.072 \mu\text{A/V}^2$

$k' = 137 \frac{\mu\text{A}}{\text{V}^2}$   
 $V_t = 0.73 \text{V}$

DETERMINATION OF  $\lambda$

RUN DC OP. POINT  $\rightarrow$  PRINT PARAMETERS.  $\rightarrow g_{ds} = \frac{I_D}{V_{DS}}$

$L = 10 \mu\text{m} \rightarrow g_{ds} = 51.69 \mu\text{A/V} \rightarrow \lambda_1 = 0.0048 \text{V}^{-1}$

$L = 1 \mu\text{m} \rightarrow g_{ds} = 126.8 \mu\text{A/V} \rightarrow \lambda_2 = 0.0172 \text{V}^{-1}$

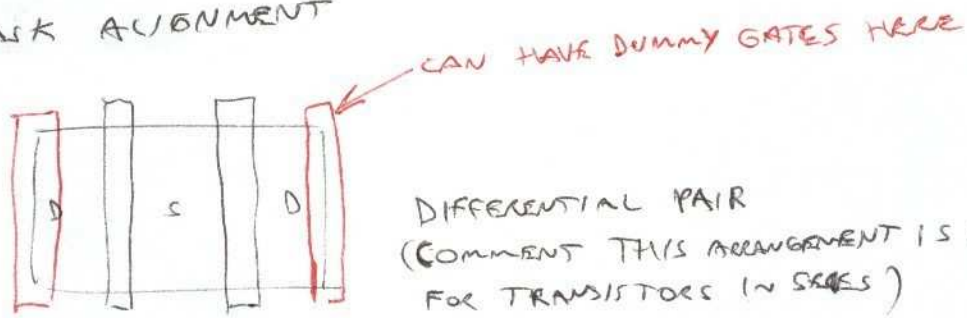
$\lambda = \frac{dI_D/dV_{DS}}{I_D} \Rightarrow \lambda_1 \approx \frac{\lambda_2}{10} \rightarrow$  NOTICE THAT DOES NOT HAPPEN.

OBSERVATION:  $g_m$ ,  $g_{mb}$  AND CAPACITANCES CAN ALSO BE OBTAINED FROM DC. OP. POINT.

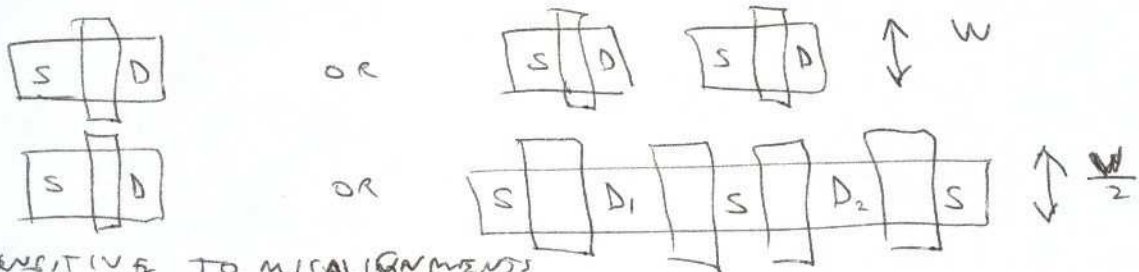
(SHOW ALSO HOW TO DETERMINE GAIN FROM DC SWEEP)

# LAYOUT CONSIDERATIONS

• EXPLAIN MASK ALIGNMENT



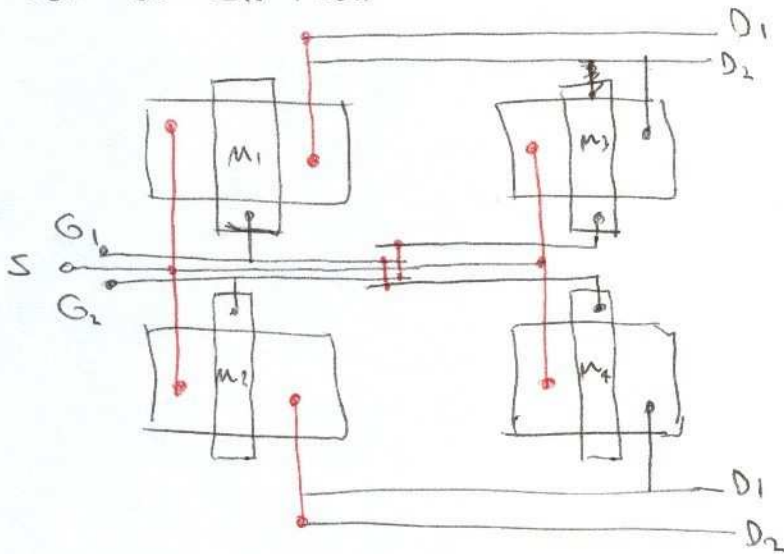
NOT SO GOOD FOR MATCHING DUE TO MASK MISALIGNMENTS.  
(DRAIN CAPACITANCES BECOME DIFFERENT)



INSENSITIVE TO MISALIGNMENTS  
BUT SENSITIVE TO PROCESS GRADIENTS.

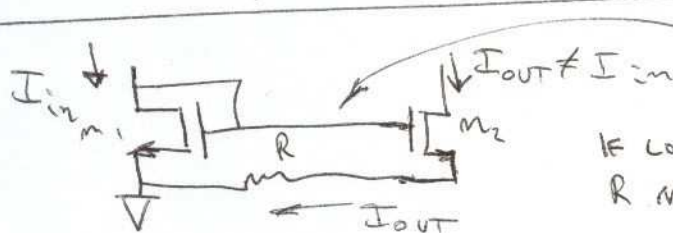
OP. AMP INPUTS ARE THE MOST SENSITIVE NODES → MUST BALANCE PARASITIC CAPACITANCES CAREFULLY

## COMMON-CENTROID



- NOTE ONLY G-S LINES CROSS OVER (OK SINCE  $C_{gs}$  IS QUITE IMPORTANT ALREADY)
- DISADVANTAGE: MORE SEPARATION BETWEEN TRANSISTORS → MAY NOT BE CONVENIENT IF GRADIENTS ARE NOT TOO STRONG.

## NOCTAGE ROUTING / CURRENTS ROUTING IN MIRRORS

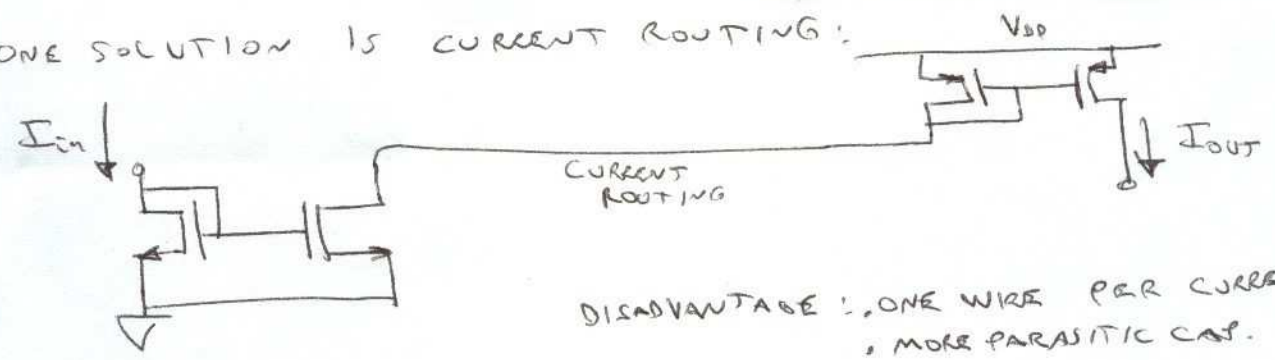


IF LONG DISTANCE  $M_1 \neq M_2$  AND  $R$  MIGHT HAVE AN EFFECT.

## VOLTAGE ROUTING

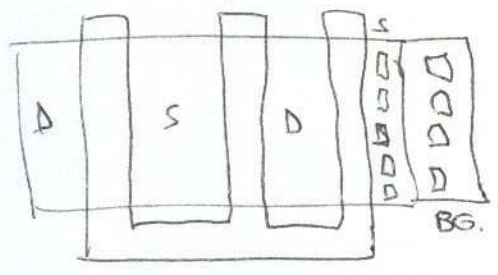


• ONE SOLUTION IS CURRENT ROUTING:



DISADVANTAGE: • ONE WIRE PER CURRENT.  
 • MORE PARASITIC CAP.

WIDE TRANSISTORS: USE MULTI-FINGERS



• FOR GOOD MATCHING: (GATE AREA) {  
 MINIMAL > 100 (μm)<sup>2</sup>  
 MODERATE > 1000 (μm)<sup>2</sup>  
 PRECISE > 10000 (μm)<sup>2</sup>

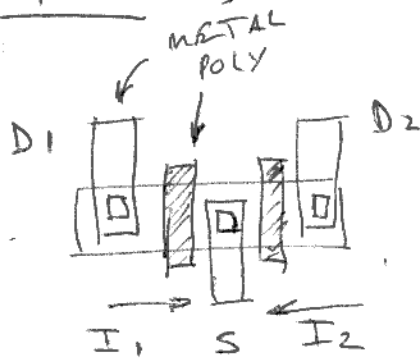
• AVOID  $L < 1\mu m$  IN MATCHING TRANSISTORS

# SUMMARY OF E. VITTOZ NOTES ON

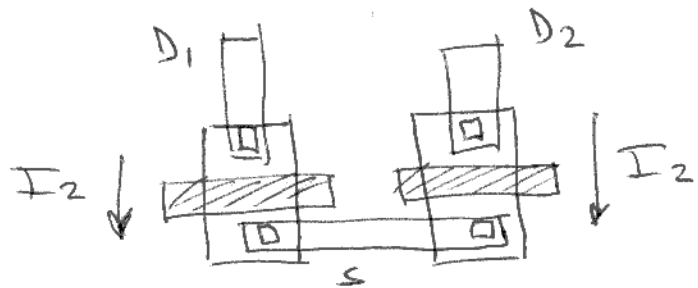
## DEVICE MATCHING (ALSO SEE § 3.4.3 SCHNEIDER/GALLUP-MONTORO)

1. SAME STRUCTURE (OF COURSE)
2. SAME TEMPERATURE (ISOTHERMS)
3. SAME SHAPE AND SIZE
4. MINIMUM DISTANCE
5. COMMON CENTROID (IF NEEDED)
6. SAME ORIENTATION
7. SAME SURROUNDINGS (DUMMY DEVICES)
8. NON-MINIMUM SIZE (RULE OF THUMB  $\geq 1 \mu\text{m}$ )

### EXAMPLE: DIFFERENTIAL PAIR



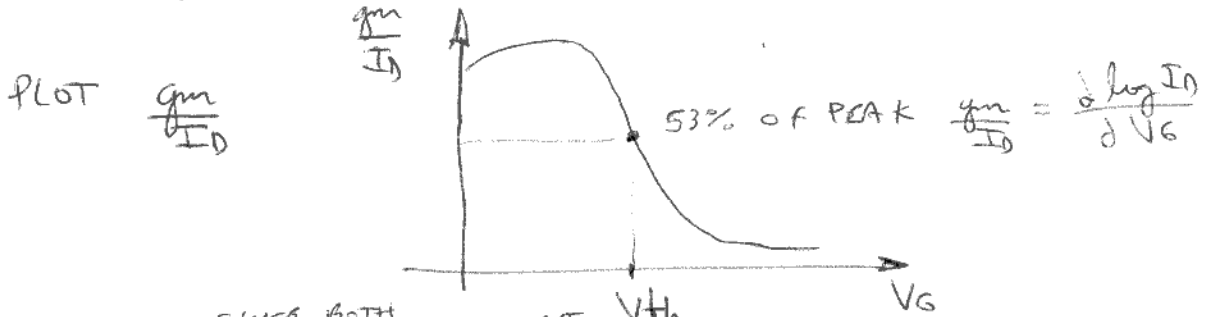
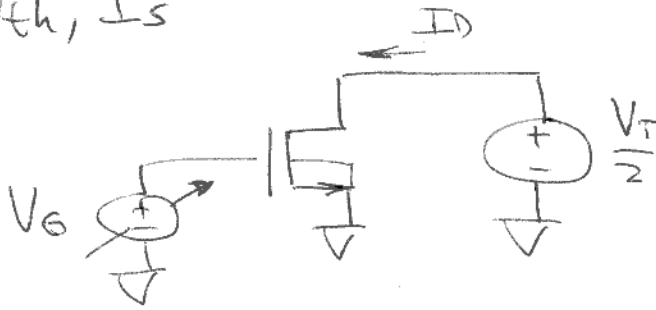
BAD  
NOT  
SAME  
ORIENTATION



GOOD

# EXTRACTION OF ACM PARAMETERS FROM SIMULATIONS

1)  $V_{th}, I_s$



SINCE BOTH  $i_f, i_r$  SIGNIFICANT

$$\frac{g_m}{I_D} = \frac{g_{m_s} - g_{m_d}}{I_D} = \frac{2 I_s}{n V_T I_D} (\sqrt{1+i_f} - \sqrt{1+i_r})$$

$$I_D = (i_f - i_r) I_s$$

WHEN  $V_G = V_{th} \Rightarrow i_f = 3$   
 $i_r \approx i_f$  SINCE  $V_G \gg V_D$

$$\frac{g_m}{I_D} \approx \frac{1}{n V_T} \frac{1}{\sqrt{1+i_f}} = \frac{1}{2 n V_T} \text{ IF } i_f = 3$$

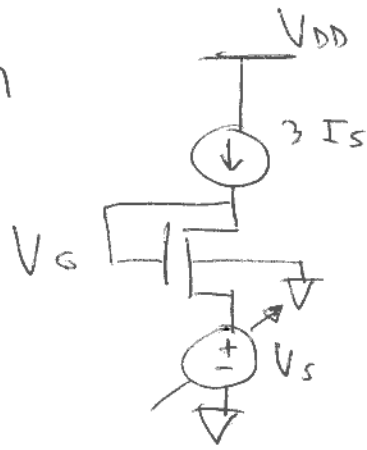
$$\frac{\sqrt{1+i_f} - \sqrt{1+i_r}}{i_f - i_r} \cdot \frac{\sqrt{1+i_f} + \sqrt{1+i_r}}{\sqrt{1+i_f} + \sqrt{1+i_r}} = \frac{1+i_f - 1-i_r}{(i_f - i_r)(\sqrt{1+i_f} + \sqrt{1+i_r})} = \frac{1}{\sqrt{1+i_f} + \sqrt{1+i_r}}$$

$i_f \approx i_r \Rightarrow \frac{g_m}{I_D} = \frac{2 I_s}{n V_T I_D} \cdot \frac{1}{2 \sqrt{1+i_f}} \rightarrow$  MORE ACCURATE 50%

$$I_D \approx \frac{2 V_{DS}}{V_T} I_s \text{ IF } V_{DS} < V_T$$

$\therefore \boxed{I_s = I_D} \Big|_{V_G = V_{th}} \rightarrow$  BUT MORE ACCURATE  $I_s = 1.13 I_D \Big|_{V_G = V_{th}}$

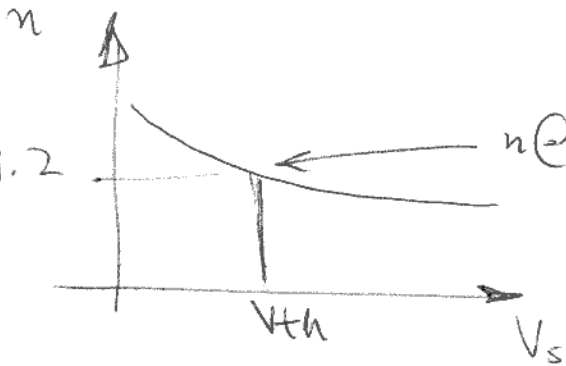
2)  $n$



$$\frac{V_p - V_s}{V_T} = \Phi(i_f)$$

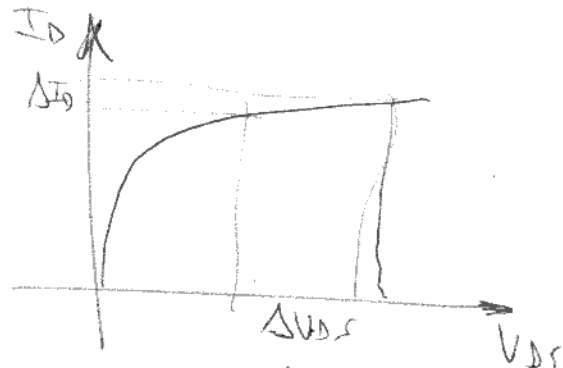
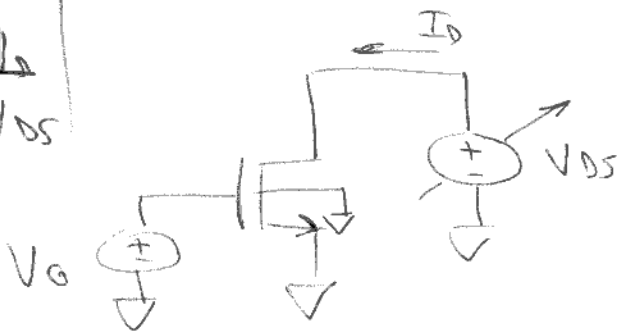
$$i_f = 3 \Rightarrow V_p = V_s = \frac{V_G - V_{th}}{n} \Rightarrow V_S = V_{th} + n V_S$$

$$n = \frac{\partial V_G}{\partial V_S}$$



$n \approx 1.2$   $n \approx V_{th}$  IS A GOOD APPROXIMATION FOR MODERATE INVERSION AND NOT TOO BAD FOR STRONG/WEAK.

3)  $\left( \frac{\partial I_D}{\partial V_{DS}} \right)$



$$\frac{\Delta V_{DS}}{\Delta I_D} = r_o = \frac{1}{\lambda I_D} = \frac{L}{\left| \frac{\partial I_D}{\partial V_{DS}} \right| I_D} \rightarrow \text{SOLVE FOR } \left| \frac{\partial I_D}{\partial V_{DS}} \right| = \frac{I_{eff}}{\lambda I_D}$$